

BOX System with NXP i.MX6

Quick Reference Guide

1st Ed – 13 April 2020

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Part No. E2017AIBAA0R

FCC Statement

THIS DEVICE COMPLIES WITH PART 15 FCC RULES. OPERATION IS SUBJECT TO THE FOLLOWING TWO CONDITIONS:

(1) THIS DEVICE MAY NOT CAUSE HARMFUL INTERFERENCE.

(2) THIS DEVICE MUST ACCEPT ANY INTERFERENCE RECEIVED INCLUDING INTERFERENCE THAT MAY CAUSE UNDESIRED OPERATION.

THIS EQUIPMENT HAS BEEN TESTED AND FOUND TO COMPLY WITH THE LIMITS FOR A CLASS "A" DIGITAL DEVICE, PURSUANT TO PART 15 OF THE FCC RULES.

THESE LIMITS ARE DESIGNED TO PROVIDE REASONABLE PROTECTION AGAINST HARMFUL INTERFERENCE WHEN THE EQUIPMENT IS OPERATED IN A COMMERCIAL ENVIRONMENT. THIS EQUIPMENT GENERATES, USES, AND CAN RADIATE RADIO FREQUENCY ENERGY AND, IF NOT INSTALLED AND USED IN ACCORDANCE WITH THE INSTRUCTION MANUAL, MAY CAUSE HARMFUL INTERFERENCE TO RADIO COMMUNICATIONS.

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1. Getting Started

1.1 Safety Precautions

Warning!



Always completely disconnect the power cord from your chassis whenever you work with the hardware. Do not make connections while the power is on. Sensitive electronic components can be damaged by sudden power surges. Only experienced electronics personnel should open the PC chassis.

Caution!



Always ground yourself to remove any static charge before touching the CPU card. Modern electronic devices are very sensitive to static electric charges. As a safety precaution, use a grounding wrist strap at all times. Place all electronic components in a static-dissipative surface or static-shielded bag when they are not in the chassis.

1.2 Packing List

• 1 x AIB-IMX6A



If any of the above items is damaged or missing, contact your retailer.

1.3 System Specifications

Component	
Mother Board	ACP-IMX6POS-B1
CPU	NXP i.MX6 Cortex-A9 Quad 1GHz CPU
CPU Cooler	• E1961213015000R , Heatsink for CPU 41*41*20mm AL A1
EMMC	• 8GB eMMC
RAM	2GB DDR3L RAM
Operating System	Linux Yocto
External I/O	
DC	DC Jack x1
	Power LED cable (Red) x1
LED	Signal LED cable (Blue) x1
Micro USB	Micro USB x1 (For OTG)
USB	Double USB 2.0 x1
HDMI	HDMI x1
	• Giga Lan x2
Lan	(Lan1 MSZ9031RNK)
	(Lan2 Intel I210)
	• COM x3
СОМ	-COM1/2 on board-DB9 (RS232/422/485)
	-COM3 Cable-DB9 (RS232)
Debug	Debug Port x1
	-Debug Cable-DB9 (Female)
Micro SD Window	Micro SD Socket x1
Mechanical	
Power Type	• DC 12~24V
Power Connector	DC Jack with lock
Туре	
Dimension	• 226mm x 121.35mm
Chassis	NCT Chassis (Black color)
Weight	• 0.3Kg
Color	Black
Fanless	• Yes
OS Support	Linux Yocto
Reliability	
EMI Test	CE/FCC Class B
Dust and Rain Test	• TBC

	• 1. PSD: 0.00454G ² /Hz , 1.5 Grms					
	2. operation mode					
Dendem Vibration	• 3. Test Frequency : 5-500Hz					
Random vibration	• 4. Test Axis : X,Y and Z axis					
Operation	• 5. 30 minutes per each axis					
	• 6. IEC 60068-2-64 Test:Fh					
	• 7. Storage : eMMC					
	1 Test Acceleration : 2G					
	• 2 Test frequency : 5~500 Hz					
Pandom vibration	• 3 Sweep : 1 Oct/ per one minute. (logarithmic)					
test (Non-operation)	• 4 Test Axis : X,Y and Z axis					
	5 Test time :10 min. each axis					
	6 System condition : Non-Operating mode					
	• 7. Reference IEC 60068-2-6 Testing procedures					
	• 1. PSD: 0.026G ² /Hz , 2.16 Grms					
	2. Non-operation mode					
Package vibration	• 3. Test Frequency : 5-500Hz					
test	• 4. Test Axis : X,Y and Z axis					
	• 5. 30 min. per each axis					
	• 6. IEC 60068-2-64 Test:Fh					
Mechanical Shock Test	• 10Grms, IEC 60068-2-27, Half Sine, 11ms					
Deekege drep test	1 One corner , three edges, six faces					
Package drop test	• 2 ISTA 2A, IEC-60068-2-32 Test:Ed					
Operating	20% 50%					
Temperature	• -20 C ~ 50 C					
Operating Humidity	• 40°C 95% relative humidity, non-condensing					
Storage	20% 70%					
Temperature	• -20 0 ~ 70 0					



Note: Specifications are subject to change without notice.

1.4 System Overview

1.4.1 Rear View



1.4.2 Right View



Connectors		
Label	Function	Note
DC 12~24V	DC Power-in connector	
Power	System Power indicator	
Status	Power Signal indicator	
OTG	Micro USB connector	
USB	Double USB2.0 connector	
HDMI	HDMI connector	
LAN1/2	RJ-45 Ethernet 1/2	
COM1/2/3	Serial port 1/2/3 connector	D-sub 9-pin, male
Debug	Debug port	
Micro SD Card	Micro SD Socket	





(Unit: mm)

2. Hardware Configuration

For advanced information, please refer to:

1- ACP-IMX6POS-B1 User's Manual

2.1 AIB-IMX6A connector mapping

2.1.1 Serial port 1 connector (COM1)





Signal	PIN	PIN	Signal
NDCDA#_485_422TX-	1	6	NC
NRXDA_485_422TX+	2	7	NRTSA#
NTXDA_422RX+	3	8	NCTSA#
NDTRA#_422RX-	4	9	NRIA#
GND	5		

2.1.2 Serial port 2 connector (COM2)





Signal	PIN	PIN	Signal
NDCDB#_485_422TX-	1	6	NC
NRXDB_485_422TX+	2	7	NRTSB#
NTXDB_422RX+	3	8	NCTSB#
NDTRB#_422RX-	4	9	NRIB#
GND	5		

2.1.3 Serial port 3 connector (COM3)



Signal	PIN	PIN	Signal
NC	1	6	NC
COM3_RXD	2	7	COM3_RTS#
COM3_TXD	3	8	COM3_CTS#
NC	4	9	COM3_RI_A
GND	5		

3. Software User Guide

3.1 Build and install U-boot & Kernel image for ACP-IMX6POS

3.1.1 Requirements

Requirements for the set up of the standalone cross-development environment:

- x86 host system (64-bit)
- recommended free disk space: 25 GB
- recommended memory size: 8 GB
- Ubuntu 14.04 (64-bit)

3.1.2 Setting Up the Standalone Cross-Development Environment

Here you can find instruction to setup development environment for Android source code for ACP-IMX6POS and the way to install it on eMMC. With this guideline, user will be able to setup the system easily and test all the functions with the system.

3.1.2.1 Perform a standard Ubuntu 14.04 (64-bit) installation.

3.1.2.2 Install additional packages:

\$ sudo apt-get install gawk wget git-core diffstat unzip texinfo gcc-multilib \ build-essential chrpath socat libsdl1.2-dev

\$ sudo apt-get install libsdl1.2-dev xterm sed cvs subversion coreutils texi2html \ docbook-utils python-pysqlite2 help2man make gcc g++ desktop-file-utils \ libgl1-mesa-dev libglu1-mesa-dev mercurial autoconf automake groff curl lzop asciidoc

\$ sudo apt-get install u-boot-tools

3.2 Get U-boot & Kernel source code and Complier

3.2.1 Get U-boot & Kernel source code

Please connect Avalue FAE to get source code.

3.2.2 Complier U-boot & Kernel image.

Please unzip the source code in your computer and enter to U-boot & Kernel source code folder.

jerry	/@AE-RISC	C:~/project/Jerry/IMX6/FSL-Kernel\$	ls
fsl	kernel	u-boot	

Enter to "u-boot" folder and type "./run.sh –j4" start to complier u-boot.

jerry@AE-RISC:~/project/Jerry/IMX6/FSL-Kernel/u-boot\$ ls										
api		disk	examples	lib	MAKEALL		scripts			
arch	config.mk		fs	lib_arm	Makefile		snapshot.commit			
board	cpu	drivers	include	lib_generic	mkconfig	README				
boards.cfg	CREDITS	dts	Kbuild	Licenses	nand_spl	run.sh	tools			

jerry@AE-RISC:~/project/Jerry/IMX6/FSL-Kernel/u-boot\$./run.sh -j4

After complier finish, there is the "out" folder would be created in u-boot source code folder.

erry@AE-RISC:~/project/Jerry/IMX6/FSL-Kernel/u-boot\$ ls										
api			examples	lib	MAKEALL	net	run.sh	tools		
	config.mk			lib arm	Makefile	out	scripts			
				lib generic	mkconfig	post	snapshot.commit			
boards.cfg	CREDITS	dts	Kbuild	Licenses	nand spl	README				

You can find the u-boot image in out folder.

jerry@A	E-RISC:~/p	erry/IMX6/F		boot/out\$ ls		
		Makefile	source		u-boot e9697imx60br emmc.imx	u-boot.map
			System.map	u-boot	u-boot.imx	u-boot.srec
common	evamples		test	u-boot hin	u-boot lds	

Enter to "kernel" folder and type "./run.sh –j4" start to complier kernel.

jerry@AE	-RISC:~/project	/Jerry/IMX			l\$ ls				
arch block COPYING	CREDITS crypto Documentation			Kbuild Kconfig kernel	lib MAINTAINERS Makefile	mm net README	REPORTING-BUGS run.sh samples		
ierrv	QAE-RISC:	/proje	ct / Jei	rv/TM	X6/FSL-Ke	ernel	/kernel\$.	/run.sh	-i4

After complier finish, there is the "out" folder would be created in Kernel source code folder.

jerry@AE	-RISC:~/project	/Jerry/IM	IX6/FSL-Kernel	<u>/kernel\$ ls</u>		
arch	Documentation	init	lib	out	scripts	virt
block	drivers	ipc	MAINTAINERS	README	security	
COPYING	firmware	Kbuild	Makefile	REPORTING-BUGS	sound	
CREDITS	fs	Kconfig		run.sh	tools	
crypto	include	kernel	net	samples	usr	

You can find the kernel image in out folder.

jerry@AE-RISC:~/p	roject/Jerry/IMX6/		/kernel/out\$ ls		
	e9697imx6e2r.dtb				usr
block	e9697imx6e3r.dtb	ipc	modules.builtin	scripts	vmlinux
crypto	firmware		modules.order	security	vmlinux.o
drivers		lib	Module.symvers		zImage e9697imx60br
e9697imx60br.dtb		Makefile	mx6dlpos.dtb	source	
e9697imx6e1r.dtb	include		mx6qpos.dtb	System.map	

3.3 Flash U-boot & Kernel image to eMMC or MicroSD

3.3.1 Flash U-boot & Kernel image to eMMC

3.3.1.1 Set the jumper to OTG mode





Mode	Description
21 00 00 00	OTG load
21 III on	eMMC boot
21	SD boot

AIB-IMX6A



3.3.1.2 Connect ACP-IMX6POS-B1 to computer through JMUSB1 by mini USB.

3.3.2 Get MFG tool

Please connect Avalue FAE to get MFG tool.

3.3.3 Flash OS to eMMC by MFG tool

3.3.3.1 Execute vbs file

Please enter to MFG-Tools\vbs and execute xxxxxxxxx-3.14.28_1.0.0-emmc.vbs.

e9697imx60br-3.14.28_1.0.0-emmc.vbs

Be9697imx60br-3.14.28_1.0.0-emmc-fast.vbs

B e9697imx60br-3.14.28_1.0.0-sd.vbs

e9697imx60br-3.14.28_1.0.0-sd-fast.vbs

After execute xxx-emmc.vbs, please press "Start" to start flash OS.

Hub 1Port 4	Unassigned	Unassigned	Unassigned	Status Information	
Drive(s):	Drive(s):	Drive(s):	Drive(s):	Successful Operations:	
HID-compliant device	No Device Connected	No Device Connected	No Device Connected	Failed Operations:	
				Failure Rate:	0
				Start	Evit
				Start	EXIC

After flash finish, please press "Stop".

MfgTool_MultiPanel (Lib	orary: 2.7.0)		-	
Hub 1Port 4	Unassigned	Unassigned	Unassigned	Status Information
Drive(s): G:	Drive(s):	Drive(s):	Drive(s):	Successful Operations: 1
Done	No Device Connected	No Device Connected	No Device Connected	Failure Rate: 0.00 %
				Stop

3.3.3.2 Boot to OS from eMMC

Set the jumper to "eMMC boot" and power on to boot to OS.





Mode	Description
	OTG load
21 III III III III III III III III III I	eMMC boot
21	SD boot

3.3.4 Flash OS to SD card by MFG tool

3.3.4.1 Please enter to MFG-Tools\vbs and execute xxxxxxxxx+4.1.15_1.0.0-sd.vbs.

e9697imx60br-3.14.28_1.0.0-emmc.vbs
Be9697imx60br-3.14.28_1.0.0-emmc-fast.vbs
e9697imx60br-3.14.28_1.0.0-sd.vbs
e9697imx60br-3.14.28_1.0.0-sd-fast.vbs

After execute xxx-emmc.vbs, please press "Start" to start flash OS.

MfgTool_MultiPanel (Library: 2.7.0	0)				- 23
Hub 1Port 4	Unassigned	Unassigned	Unassigned	Status Information	
Drive(s):	Drive(s):	Drive(s):	Drive(s):	Successful Operations:	0
				Failed Operations:	0
HID-compliant device	No Device Connected	No Device Connected	No Device Connected	Failure Rate:	0 %
				Start	Exit

After flash finish, please press "Stop".

MfgTool_MultiPanel (Library: 2.7	.0)	ough a decline a appropriate			- 23
Hub 1Port 4 Drive(s): G:	Unassigned Drive(s):	Unassigned Drive(s):	Unassigned Drive(s):	Status Information Successful Operations: Failed Operations:	1 0
				Failure Rate:	0.00 %

3.3.4.2 Boot to OS from SD card

Set the jumper to "SD boot" and power on to boot to OS.





Mode	Description
21	OTG load
21	eMMC boot
21	SD boot

